

Naam:
Adres:
Postcode en
Woonplaats:

Studentnummer:
Studierichting:
Jaar van eerste inschrijving:

Bladnr.: 1/4
Tentamen: Vectoranalyse
Datum:
Naam docent:

27 1 ①
⑫

Er geldt $z^2 = 1 - x^2 - y^2$

das z kan uitgedrukt worden in x en y .

~~raakvlak in punt (x_0, y_0, z_0)~~ $\Rightarrow z = z_0 + \frac{\partial z}{\partial x}(x_0, y_0)(x - x_0) + \frac{\partial z}{\partial y}(x_0, y_0)(y - y_0)$

$$z = \pm \sqrt{1 - x^2 - y^2}$$

$$\frac{\partial z}{\partial x} = \pm \frac{1}{2\sqrt{1-x^2-y^2}} \cdot -2x = \pm \frac{-x}{\sqrt{1-x^2-y^2}}$$

$$\frac{\partial z}{\partial y} = \pm \frac{1}{2\sqrt{1-x^2-y^2}} \cdot -2y = \pm \frac{-y}{\sqrt{1-x^2-y^2}}$$

~~raakvlak aan S in punt (x_0, y_0, z_0)~~

~~...~~

Er geldt dat ∇z de normaalvector is.

$\nabla z(x_0, y_0, z_0)$

$$\Rightarrow \nabla z \cdot (\vec{x} - \vec{x}_0) = 0$$

$$\Rightarrow \begin{pmatrix} \frac{\partial z}{\partial x}(x_0, y_0) \\ \frac{\partial z}{\partial y}(x_0, y_0) \\ 1 \end{pmatrix} \cdot \begin{pmatrix} x - x_0 \\ y - y_0 \\ z - z_0 \end{pmatrix} = 0$$

$$\Rightarrow \pm \left(\frac{-x_0}{\sqrt{1-x_0^2-y_0^2}} \cdot (x - x_0) \right) + \left(\pm \frac{-y_0}{\sqrt{1-x_0^2-y_0^2}} \cdot (y - y_0) \right) + z - z_0 = 0$$

Omdat $z_0 = \pm \sqrt{1-x_0^2-y_0^2}$

~~$\Rightarrow \pm \left(\frac{-x_0}{z_0} \cdot (x - x_0) \right) + \left(\pm \frac{-y_0}{z_0} \cdot (y - y_0) \right) + z - z_0 = 0$~~
 ~~$\Rightarrow \pm \left(\frac{-x_0}{z_0} \cdot (x - x_0) \right) + \left(\pm \frac{-y_0}{z_0} \cdot (y - y_0) \right) + z - z_0 = 0$~~

$$\Rightarrow \left(\frac{-x_0}{z_0} \cdot (x - x_0) \right) + \left(\frac{-y_0}{z_0} \cdot (y - y_0) \right) + z - z_0 = 0$$

$$-x_0 x + x_0^2 - y_0 y + y_0^2 - 2z_0 + 2z_0^2 = 0$$

$$\Rightarrow -(x_0 x + y_0 y + 2z_0 z) + x_0^2 + y_0^2 + 2z_0^2 = 0$$

$$\Rightarrow x_0 x + y_0 y + 2z_0 z = x_0^2 + y_0^2 + 2z_0^2$$

$$\bullet x^2 + y^2 + z^2 = 1 \Rightarrow \text{~~...}~~$$

$$\Rightarrow x_0^2 + y_0^2 + 2z_0^2 = 1$$

$$\Rightarrow \boxed{x_0 x + y_0 y + 2z_0 z = 1} \quad \text{QED}$$

(12)

(2)

Er is maar één raakvlak aan S in het punt $(0,0,2)$, namelijk die door het punt zelf omdat de raakvlak een bol raakt door de bol gaat.

$$\text{(Bol raakt } (0,0,2) \text{ op } (0,0,2))$$

$$\Rightarrow \text{...}$$

$$\text{evenwijdig aan } x\text{-as} \Rightarrow \frac{\partial z}{\partial x} = 0$$

$$\text{~~...}~~$$

Het raakvlak aan S moet ook door het punt $(0,0,2)$ gaan.

Voor een raakvlak aan S geldt $x_0 x + y_0 y + 2z_0 z = 1$

$$(x, y, z) = (0, 0, 2) \Rightarrow 2z_0 = 1 \Rightarrow z_0 = \frac{1}{2}$$

Het moet een raakvlak in $z_0 = \frac{1}{2}$ zijn. \curvearrowright

$$\Rightarrow \left. \begin{array}{l} x_0^2 + y_0^2 + 2z_0^2 = 1 \\ z_0 = \frac{1}{2} \end{array} \right\} x_0^2 + y_0^2 = \frac{3}{4}$$

Ook evenwijdig aan de x -as, dus $\frac{\partial y}{\partial x} = 0$

$$\Rightarrow y = \pm \sqrt{\frac{3}{4} - x_0^2}$$

$$\Rightarrow \frac{\partial y}{\partial x} = \frac{1}{2\sqrt{\frac{3}{4} - x_0^2}} \cdot -2x = \pm \frac{-x}{\sqrt{\frac{3}{4} - x_0^2}}$$

Vervolg ①

$$\frac{\partial y}{\partial x} = \pm \sqrt{\frac{-x}{\frac{3}{4} - x^2}} = 0$$

$$\Rightarrow x=0 \quad \text{als} \quad \frac{3}{4} - x^2 \neq 0$$

$$x^2 \neq \frac{3}{4}$$

$$x \neq \sqrt{\frac{3}{4}}$$

$$\left. \begin{array}{l} \\ \\ \end{array} \right\} \text{dus } x=0$$

 ~~$x=0 \Rightarrow y=0$~~

$$\text{Dus } z_0 = \frac{1}{2} \quad \text{en } x=0$$

$$\text{en } x_0^2 + y_0^2 = \frac{3}{4}$$

$$x=0 \Rightarrow y_0 = \sqrt{\frac{3}{4}}$$

$$x = \sqrt{\frac{3}{4}} \Rightarrow y_0 = 0$$

$$\left(0, \pm \frac{\sqrt{3}}{2}, \frac{1}{2}\right)$$

Dus de punten van S waarin het raakvlak door het punt $(0,0,1)$ gaat en evenwijdig is aan de x -as,

$$\text{zijn } \left(0, \sqrt{\frac{3}{4}}, \frac{1}{2}\right) \text{ en } \left(\sqrt{\frac{3}{4}}, 0, \frac{1}{2}\right)$$

$$\boxed{2} \quad \left[\begin{array}{cc} \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} \end{array} \right] = \left[\begin{array}{cc} \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{array} \right] \left[\begin{array}{cc} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{array} \right]$$

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$$\Rightarrow \left[\begin{array}{cc} \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} \end{array} \right] = \left[\begin{array}{cc} \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{array} \right] \left[\begin{array}{cc} e^r \cos \theta & -e^r \sin \theta \\ e^r \sin \theta & e^r \cos \theta \end{array} \right]$$

$$\rightarrow \frac{\partial z}{\partial r} = \frac{\partial g}{\partial x} e^r \cos \theta + \frac{\partial g}{\partial y} e^r \sin \theta$$

$$\frac{\partial z}{\partial \theta} = -\frac{\partial g}{\partial x} e^r \sin \theta + \frac{\partial g}{\partial y} e^r \cos \theta$$

$$\textcircled{2} \quad \frac{\partial z}{\partial r} = \frac{\partial g}{\partial x} e^r \cos \theta + \frac{\partial g}{\partial y} e^r \sin \theta$$

$$6 \quad \frac{\partial z}{\partial \theta} = -\frac{\partial g}{\partial x} e^r \sin \theta + \frac{\partial g}{\partial y} e^r \cos \theta$$

$$\Rightarrow \frac{\partial g}{\partial x} e^r \cos \theta = \frac{\partial z}{\partial r} - \frac{\partial g}{\partial y} e^r \sin \theta$$

$$e^r \cos \theta \frac{\partial g}{\partial y} = \frac{\partial z}{\partial \theta} + \frac{\partial g}{\partial x} e^r \sin \theta$$

~~$$\frac{\partial g}{\partial x} \frac{\partial z}{\partial r} = \frac{\partial z}{\partial r} \frac{\partial g}{\partial x}$$~~

$$e^r \cos \theta = x$$

$$e^r \sin \theta = y$$

$$\Rightarrow \frac{\partial g}{\partial x} \cdot x = \frac{\partial z}{\partial r} - \frac{\partial g}{\partial y} \cdot y$$

$$\frac{\partial g}{\partial y} \cdot y = \frac{\partial z}{\partial \theta} + \frac{\partial g}{\partial x} \cdot x$$

$$\frac{\partial g}{\partial x} = \frac{\partial z}{\partial r} \frac{1}{x} - \frac{\partial g}{\partial y} \frac{y}{x}$$

$$\Rightarrow \frac{\partial g}{\partial y} \cdot x = \frac{\partial z}{\partial \theta} + \left(\frac{\partial z}{\partial r} \cdot \frac{1}{x} - \frac{\partial g}{\partial y} \frac{y}{x} \right) \cdot y$$

$$\frac{\partial g}{\partial y} \cdot x = \frac{\partial z}{\partial \theta} + \frac{\partial z}{\partial r} \cdot \frac{y}{x} - \frac{\partial g}{\partial y} \cdot \frac{y^2}{x}$$

$$\frac{\partial g}{\partial y} \cdot x + \frac{\partial g}{\partial y} \frac{y^2}{x} = \frac{\partial z}{\partial \theta} + \frac{\partial z}{\partial r} \frac{y}{x}$$

$$\frac{\partial g}{\partial y} \left(x + \frac{y^2}{x} \right) = \frac{\partial z}{\partial \theta} + \frac{\partial z}{\partial r} \left(\frac{y}{x} \right)$$

~~$$\frac{\partial g}{\partial y} = \frac{\partial z}{\partial \theta} + \frac{\partial z}{\partial r} \frac{\partial g}{\partial y}$$~~

$$\frac{\partial g}{\partial y} = \frac{\frac{\partial z}{\partial \theta} + \frac{\partial z}{\partial r} \left(\frac{y}{x} \right)}{\left(x + \frac{y^2}{x} \right)}$$

$$\begin{bmatrix} \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial r} \end{bmatrix} = \begin{bmatrix} \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{bmatrix} \begin{bmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial r} \end{bmatrix} = \begin{bmatrix} \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{bmatrix} \cdot A$$

$$\Rightarrow \begin{bmatrix} \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial r} \end{bmatrix} \cdot A^{-1} = \begin{bmatrix} \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{bmatrix} \Rightarrow A^{-1} = e^{-r} \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

$$\Rightarrow \frac{\partial g}{\partial x} = \left(\frac{\partial z}{\partial \theta} \cos \theta + \frac{\partial z}{\partial r} \sin \theta \right) e^{-r}$$

$$\Rightarrow \frac{\partial g}{\partial y} = \left(-\frac{\partial z}{\partial \theta} \sin \theta + \frac{\partial z}{\partial r} \cos \theta \right) e^{-r}$$

MATRIX PRODUCT
verkeerd geval used

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$$\frac{\partial z}{\partial r} = \frac{\partial g}{\partial x} e^r \cos \theta + \frac{\partial g}{\partial y} e^r \sin \theta$$

z

$$\frac{\partial z}{\partial \theta} = -\frac{\partial g}{\partial x} e^r \sin \theta + \frac{\partial g}{\partial y} e^r \cos \theta$$

TOTAAL punten opgave 2:

$$\frac{\partial g}{\partial x} = \frac{\partial z}{\partial \theta} \cos \theta + \frac{\partial z}{\partial r} \sin \theta$$

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$$\frac{\partial g}{\partial y} = -\frac{\partial z}{\partial \theta} \sin \theta + \frac{\partial z}{\partial r} \cos \theta$$

$$\frac{\partial^2 z}{\partial r^2} = \frac{\partial^2 g}{\partial x \partial r} e^r \cos \theta + \frac{\partial g}{\partial x} \cdot e^r \cdot \cos \theta + \frac{\partial g}{\partial y \partial r} e^r \sin \theta + \frac{\partial g}{\partial y} e^r \sin \theta$$

$$\frac{\partial^2 z}{\partial \theta^2} = -\frac{\partial g}{\partial x \partial \theta} e^r \sin \theta - \frac{\partial g}{\partial x} e^r \cos \theta + \frac{\partial g}{\partial y \partial \theta} e^r \cos \theta - \frac{\partial g}{\partial y} e^r \sin \theta$$

$$\frac{\partial g}{\partial x} = \frac{\partial z}{\partial \theta} \frac{x}{e^r} + \frac{\partial z}{\partial r} \frac{y}{e^r}$$

$$\frac{\partial g}{\partial y} = -\frac{\partial z}{\partial \theta} \frac{y}{e^r} + \frac{\partial z}{\partial r} \frac{x}{e^r}$$

ook functie van x

$$\Rightarrow \frac{\partial^2 g}{\partial x^2} = \frac{\partial^2 z}{\partial \theta \partial x} \frac{x}{e^r} + \frac{\partial z}{\partial \theta} \frac{1}{e^r} + \frac{\partial^2 z}{\partial r \partial x} \frac{y}{e^r}$$

$$\frac{\partial^2 g}{\partial y^2} = -\frac{\partial^2 z}{\partial \theta \partial y} \frac{y}{e^r} - \frac{\partial z}{\partial \theta} \frac{1}{e^r} + \frac{\partial^2 z}{\partial r \partial y} \frac{x}{e^r}$$

$$\frac{\partial^2 g}{\partial x^2} + \frac{\partial^2 g}{\partial y^2} = \frac{\partial^2 z}{\partial \theta \partial x} \frac{x}{e^r} + \frac{\partial^2 z}{\partial r \partial x} \frac{y}{e^r} - \frac{\partial^2 z}{\partial \theta \partial y} \frac{y}{e^r} + \frac{\partial^2 z}{\partial r \partial y} \frac{x}{e^r}$$

$$\frac{\partial^2 z}{\partial r^2} + \frac{\partial^2 z}{\partial \theta^2} = \frac{\partial^2 g}{\partial x \partial r} e^r \cos \theta + \frac{\partial g}{\partial y \partial r} e^r \sin \theta - \frac{\partial g}{\partial x \partial \theta} e^r \sin \theta + \frac{\partial g}{\partial y \partial \theta} e^r \cos \theta$$

$$\frac{\partial^2 g}{\partial x^2} + \frac{\partial^2 g}{\partial y^2} = \frac{1}{e^r} \left(\frac{\partial^2 z}{\partial \theta \partial x} x + \frac{\partial^2 z}{\partial r \partial x} y - \frac{\partial^2 z}{\partial \theta \partial y} y + \frac{\partial^2 z}{\partial r \partial y} x \right)$$

$$\frac{\partial^2 z}{\partial r^2} + \frac{\partial^2 z}{\partial \theta^2} = \left(\frac{\partial^2 g}{\partial x \partial r} x + \frac{\partial g}{\partial y \partial r} y - \frac{\partial g}{\partial x \partial \theta} y + \frac{\partial g}{\partial y \partial \theta} x \right)$$

$$\Rightarrow \frac{\partial^2 g}{\partial x^2} + \frac{\partial^2 g}{\partial y^2} = e^{-2r} \left(\frac{\partial^2 z}{\partial r^2} + \frac{\partial^2 z}{\partial \theta^2} \right)$$

$$\boxed{3} \text{ ① } \nabla f(p_0) = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \\ \frac{\partial f}{\partial z} \end{pmatrix}$$

$$\Rightarrow \frac{\partial f}{\partial z} = 1 \neq 0$$

De impliciete-functie theorema zegt dat als $f(x, y, z)$ (impliciet gedefinieerde functie) en als de partiele afgeleide naar één van de variabelen niet nul is, de functie omgeschreven kan worden zodat ~~er~~ een functie ontstaat waarin alle overgebleven variabelen in die ene worden uitgedrukt.

In de buurt van p_0 , geldt $\frac{\partial f}{\partial z} = 1 \neq 0$

Dus volgens impliciete functie theorema

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$$\Rightarrow z = g(x, y)$$

Een C_1 functie, waarbij $z_0 = g(x_0, y_0)$

$$\text{② } \frac{\partial z}{\partial x} = \frac{\partial g(x, y)}{\partial x} = \frac{\partial g}{\partial x} \cdot \frac{\partial x}{\partial x} + \frac{\partial g}{\partial y} \cdot \frac{\partial y}{\partial x} \quad ?$$

$$= \frac{\partial g}{\partial x} + \frac{\partial g}{\partial y} \cdot \frac{\partial y}{\partial x}$$

$$\frac{\partial z}{\partial y} = \frac{\partial g(x, y)}{\partial y} = \frac{\partial g}{\partial y} + \frac{\partial g}{\partial x} \cdot \frac{\partial x}{\partial y}$$

$$\Gamma_n(x_0, y_0) \Rightarrow \frac{\partial f}{\partial x} = 0 \quad \text{en} \quad \frac{\partial f}{\partial y} = 0$$

waarm?

$$\Rightarrow \frac{\partial z}{\partial x} = 0 \quad \text{en} \quad \frac{\partial z}{\partial y} = 0$$

Dus (x_0, y_0) is een kritiek punt van $g(x, y)$.

Afdeling Wiskunde en Informatica R.U.G.

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$$\frac{\partial^2 f}{\partial x^2}(p_0) \frac{\partial^2 f}{\partial y^2}(p_0) - \left(\frac{\partial^2 f}{\partial x \partial y}(p_0)\right)^2 > 0$$

$$\frac{\partial^2 f}{\partial x^2}(p_0) \frac{\partial^2 f}{\partial y^2}(p_0) > \left(\frac{\partial^2 f}{\partial x \partial y}(p_0)\right)^2$$

De Hessian $\det \begin{bmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{bmatrix}$ is groter dan 0.

Dus x_0 is een maximum (of een minimum), geen zadel (figuur).

Als $\frac{\partial^2 f}{\partial x^2}(p_0) < 0$, dan $\frac{\partial^2 f}{\partial y^2} > 0$,

dan $\frac{\partial^2 g}{\partial y^2} > 0$, dus dat heeft g een lokaal minimum.

Vice versa, als $\frac{\partial^2 f}{\partial x^2}(p_0) > 0$, dan heeft g een

lokaal maximum in (x_0, y_0)